



Color Histogram Normalization using Matlab and Applications in CBIR

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Outline

- n Introduction
- n Demonstration of the algorithm
- n Mathematical background
- n Computational background: Matlab
- n Presentation of the algorithm
- n Evaluation of the test
- n Conclusion

Introduction (1)

- n Retrieval in large image databases
 - n Textual key based
 - n Key generation is subjective and manual
 - n Retrieval is errorless
 - n Content Based Image Retrieval (CBIR)
 - n Key generation is automatic (possibly time consuming)
 - n Noise is unavoidable

Introduction (2)

- n If a new key is introduced, the whole database has to be reindexed.
- n In textual key based retrieval the reindexing requires a lot of human work, but in CBIR case it requires only a lot of computing.

Introduction (3)

- n CBIR

- n Low level

- n Color, shape, texture

- n High level

- n Image interpretation

- n Image understanding

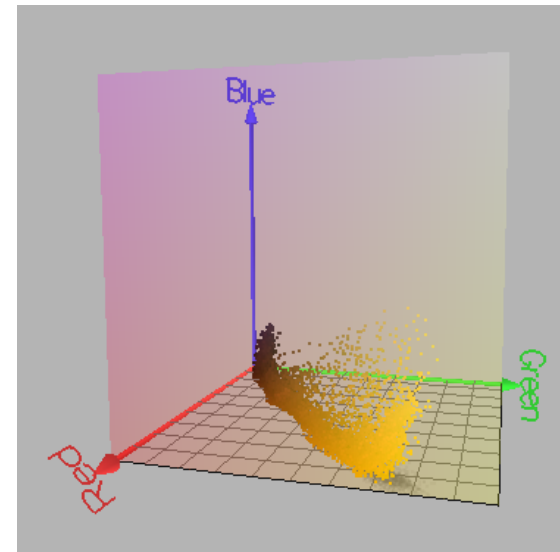
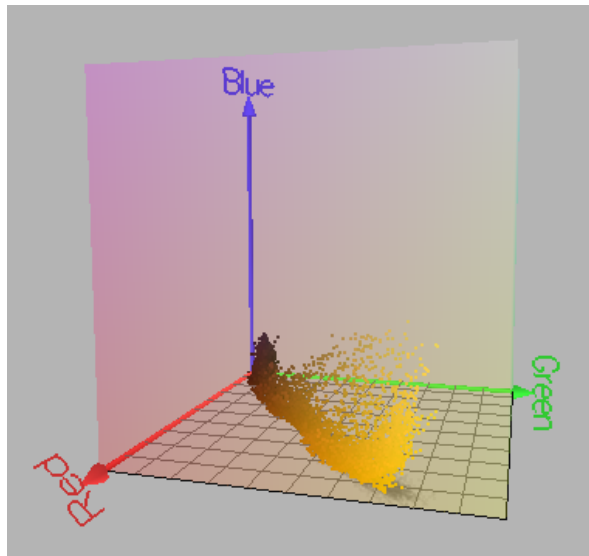
Introduction (4)

- n Typical task of low level CBIR
 - n Search for a given object using similarity distance based on content keys
- n One way of defining similarity distance is to use color histograms – we concentrate on this approach in the present talk

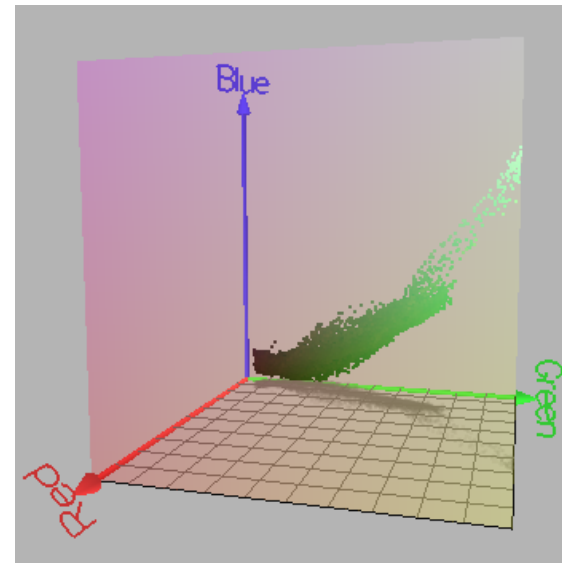
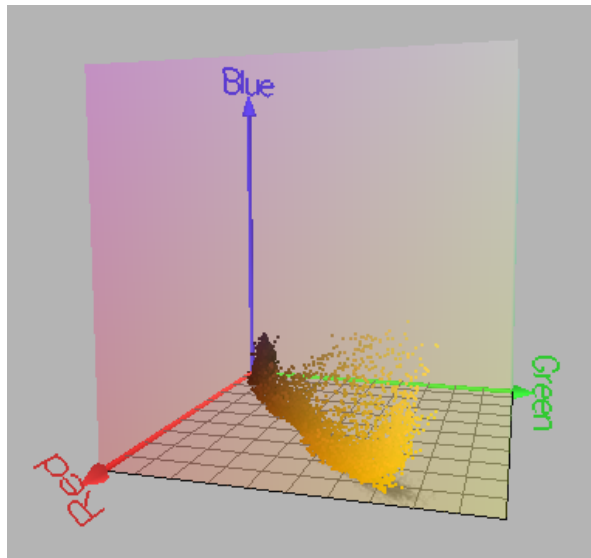
Demonstration of the algorithm



Image versions and their histograms



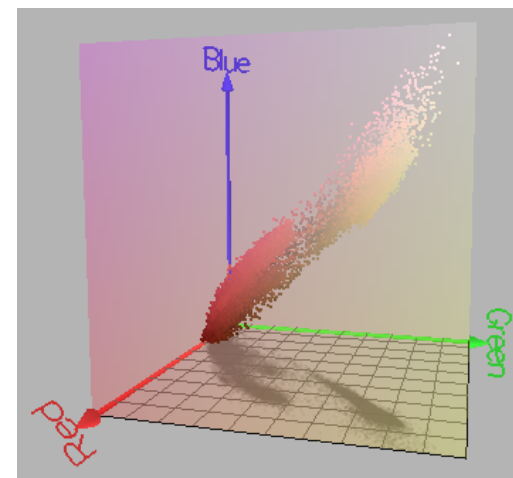
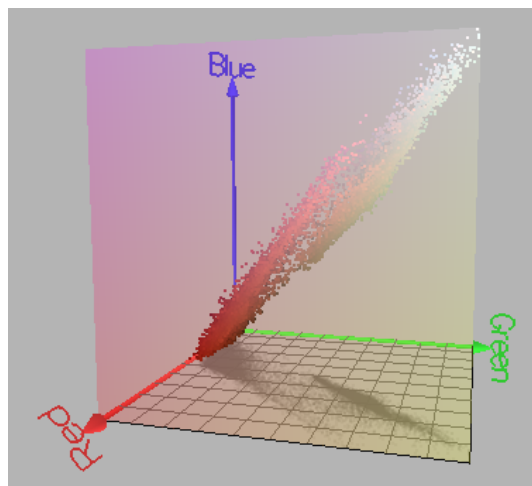
Two images and their histograms



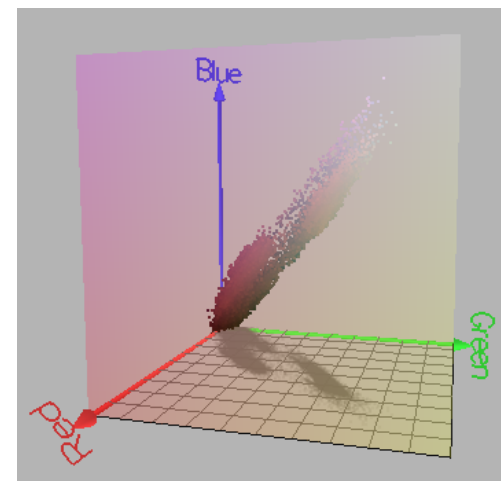
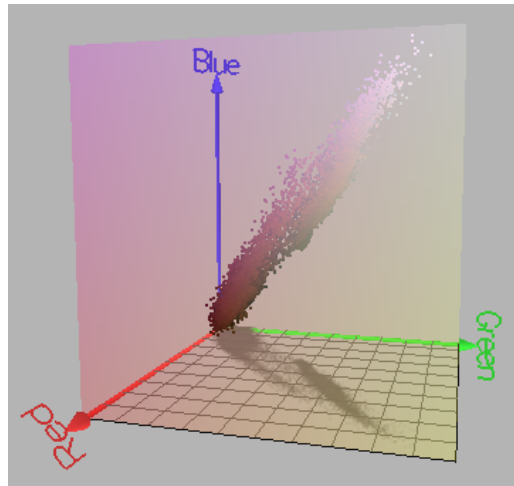
Similarity distance between two image histograms

$$d_{\text{Euclid}}(hx, hy) = \sqrt{\sum_{r=1}^4 \sum_{g=1}^4 \sum_{b=1}^4 (hx_{rgb} - hy_{rgb})^2}$$

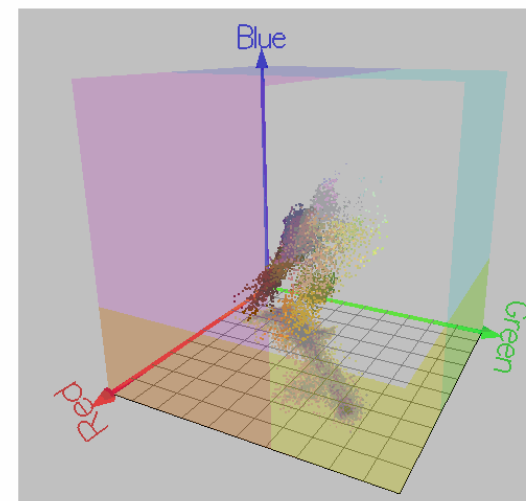
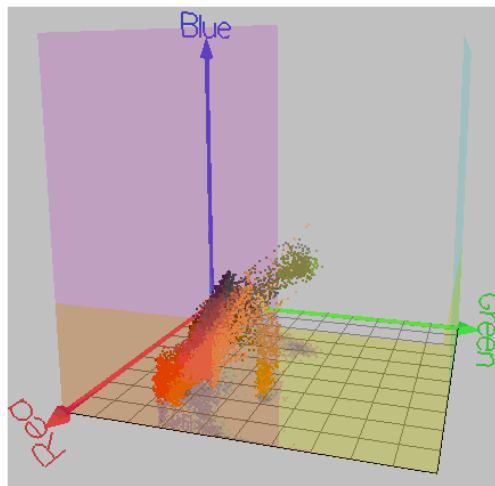
Different illuminations



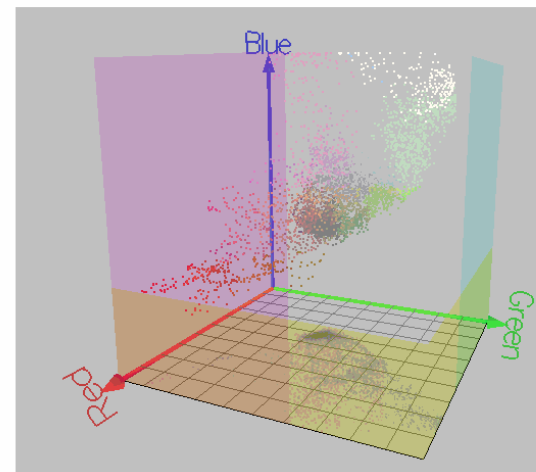
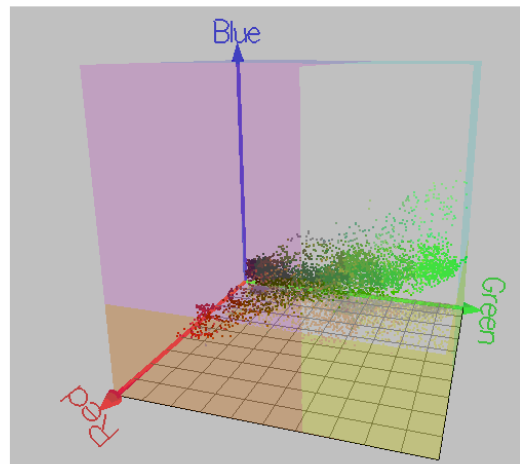
Normalized versions



Normalization may change image outlook



Normalization may change image outlook



Mathematical background



Color cluster analysis

$$n \quad f = [f_{ij}] \quad i = 1, \dots, M; j = 1, \dots, N$$

1. Compute the cluster center of all pixels f by $m = E[f]$. m is a vector which points to the center of gravity.
2. $C = E[(f - m)(f - m)^T]$
The eigenvalues $(\lambda_1, \lambda_2, \lambda_3)$ and eigenvectors of C are computed directly.
3. Denote the eigenvector belonging to the largest eigenvalue by $v = (a, b, c)^T$.

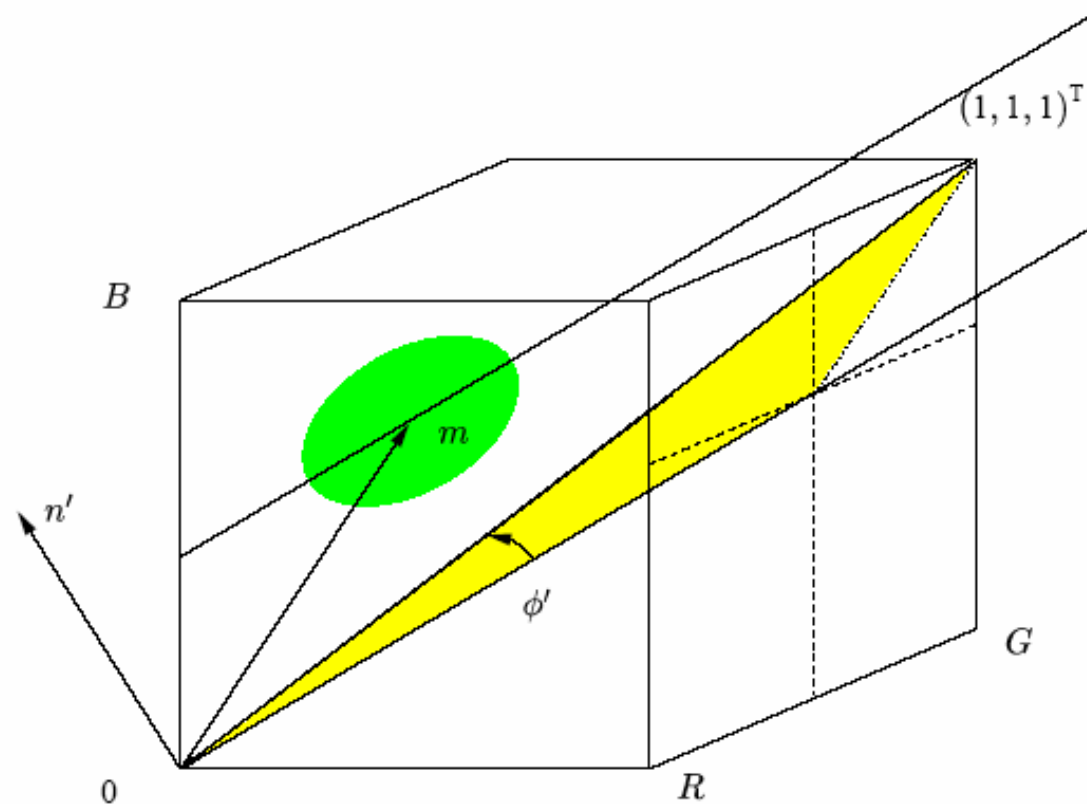
Rodrigues formula

Rotating v along n (n is a unit vector) by θ : Rv , where

$$R = I + U(n) \sin \theta + U(n)^2 (1 - \cos \theta)$$

$$U(n) = \begin{pmatrix} 0 & -n_3 & n_2 \\ n_3 & 0 & -n_1 \\ -n_2 & n_1 & 0 \end{pmatrix}$$

Color rotation in RGB-space



Color rotation in RGB-space

$$n' = (a, b, c)^T \times \frac{1}{\sqrt{3}} (1, 1, 1)^T$$

$$\cos q' = (a, b, c)^T \cdot \frac{1}{\sqrt{3}} (1, 1, 1)^T$$

Color rotation in RGB-space

4. Use the Rodrigues formula in order to rotate with θ' around n' .
5. Shift the image along the main axis of the RGB-cube by $(128, 128, 128)^T$.
6. Clip the overflows above 255 and the underflows under 0.

Computational background

Fundamentals of MATLAB



Presentation of the algorithm



MATLAB code

```
function color_normalization(FILENAME, OUTPUT);

inp_image = imread(FILENAME); % read input image
[m,n,d]=size(inp_image);      % get size of input image
f=double(inp_image);          % double needed for computations
M=zeros(m*n,3);
z=1;
mv=mean(mean(f));             % a vector containing the mean r,g and b value
v1=[mv(1),mv(2),mv(3)];      % means in red, green and blue
```

MATLAB code

```
for i=1:m
    for j=1:n
        v=[f(i,j,1),f(i,j,2),f(i,j,3)]; % image pixel at i,j
        M(z,:) = v - v1; % image normed to mean zero
        z = z + 1;
    end
end
C = cov(M); % covariance computed using Matlab cov function
```


MATLAB code

```
%find eigenvalues and eigenvectors of C.  
[V,D]=eig(C); % computes the eigenvectors(V) and eigenvalues  
              (diagonal elements of D) of the color cluster C  
%get the max. eigenvalue meig and the corresponding eigenvector ev0.  
meig = max(max(D)); % computes the maximum eigenvalue of C.  
                    Could also be norm(C)  
if(meig==D(1,1)), ev0=V(:,1);, end  
if(meig==D(2,2)), ev0=V(:,2);, end  
if(meig==D(3,3)), ev0=V(:,3);, end  
% selects the eigenvector belonging to the greatest eigenvalue
```

MATLAB code

```
Idmat =eye(3);    % identity matrix of dimension 3
wbaxis=[1;1;1]/sqrt(3); % unit vector pointing from origin along the main
                        diagonal
nvec  = cross(ev0,wbaxis);    % rotation axis , cross(A,B)=AxB
cosphi = dot(ev0,wbaxis)    % dot product, i.e. sum((ev0.*wbaxis))
sinphi = norm(nvec); % sinphi is the length of the cross product of two
                    unit vectors

%normalized rotation axis.
nvec  = nvec/sinphi; % normalize nvec
```

MATLAB code

```
if(cosphi>0.99)
    f=uint8(f);
    imwrite(f,OUTPUT); %in this case we dont normalize, output is
                        input etc.
else
    % we normalize
    n3 = nvec(3); n2 = nvec(2); n1 = nvec(1);
    % remember: this is a unit vector along the rotation axis
    U = [[ 0 -n3 n2]; [ n3 0 -n1]; [ -n2 n1 0]];
    U2 = U*U;
    Rphi = Idmat + (U*sinphi) + (U2*(1-cosphi));
```

MATLAB code

```
n0 = [0 0 0]';
n255 = [255 255 255]';
for i=1:m
    for j=1:n
        s(1)= f(i,j,1)-mv(1); % compute vector s of normalized image at i,j
        s(2)= f(i,j,2)-mv(2);
        s(3)= f(i,j,3)-mv(3);
        t = Rphi*s' ; % s transposed, as s is row vector, then rotated
        tt = floor(t + [128 128 128]'); % shift to middle of cube and
                                         make it integer
```

MATLAB code

```
tt = max(tt,n0);           % handling underflow
tt = min(tt,n255);        % handling overflow

    g(i,j,:)=tt;
end
end

g=uint8(g);
imwrite(g,OUTPUT);
end    % end of normalization
```

Evaluation of the test



Test databases

- n 5 objects
 - n Alternative color cubes
 - n 3 illuminations
 - n 3 background
-
- n 90 images



Some test results (without normalization)

DSC01151.JPG



DSC01093.JPG



DSC01153.JPG



38.2203

43.2638

DSC01152.JPG



DSC01154.JPG



DSC01155.JPG



44.7228

45.8023

51.6711

Some test results (with normalization)

n_DSC01151.JPG



n_DSC01150.JPG



n_DSC01092.JPG



52.6808

78.7583

n_DSC01103.JPG



n_DSC01102.JPG



n_DSC01161.JPG



107.3023

114.1666

116.0299

Conclusions



References

- n Paulus, D., Csink, L., and Niemann, H.: Color Cluster Rotation. In: Proc. of International Conference on Image Processing, 1998, pp. 161-165
- n Sergyán, Sz.: Special Distances of Image Color Histograms. In: Proc. of 5th Joint Conference on Mathematics and Computer Science, Debrecen, Hungary, June 9-12, 2004, pp. 92

Thank you for your attention!

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